

## Processing the Data

- IDL environment
- Noise, bandpass, baseline calibration
- Flagging, visual inspection
- Signal extraction , phase 1
- Continuum sources
- Gridding, tile cubes
- Signal extraction, phase 2

Tasks needed

Data Products





### ALFALFA:

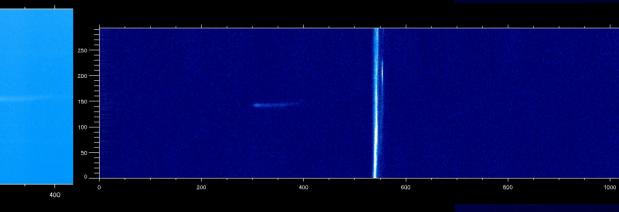
- Park telescope at meridian (minimal intrusion); rotate array to 19deg (equal Dec spacing of beams); sky drifts, cover 100 MHz BW centered at 1385 MHz.
- Sample at the rate of 1 record per second, producing drift scans of 600 sec:
  - 600 x 2 pol x 7 beams x 4096 sp. Channels = 200 MB
- Convert FITS files to IDL structures
- Bandpass subtraction, baselining, calibration, visual inspection within weeks: level I Data Products
- After second pass: gridding, Tile Data Cubes (4x5deg), automated signal extraction: level II Data Products
- Catalogs (level III Products), cross-referencing, web access via NVO

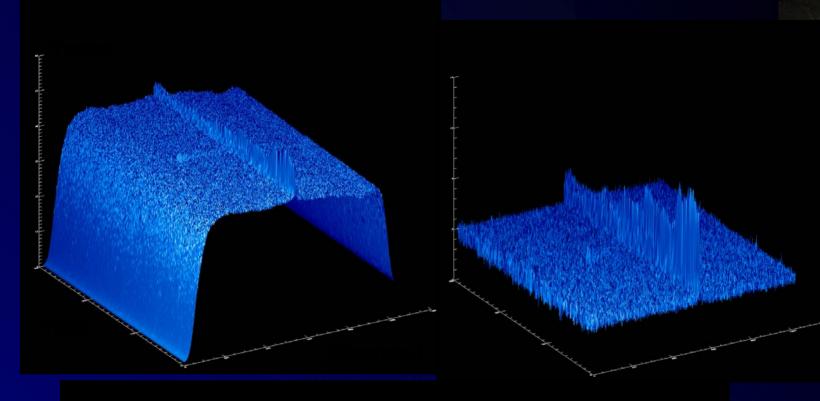
- 1. At the telescope: convert FITS file to IDL structures and .sav files
- 2. Within days to weeks: create calibration structures (ncalib) for
  - observing session (calib1, calib2)
  - run bpdgui, which will use ncalib to noisecalibrate all data in the observing session, obtain a bandpass BP solution and apply it for each drift scan in the session, obtain a continuum map of the drift,
    - create a **pos** structure, a **calsession** structure, various masks for continuum, rfi features.
- 3. First detailed visual inspection of data:
  - run flagbb which "flags bad boxes" in the data, one beam/pol map at a time
- 4. Run automated signal extraction algorithm: extract and produce source candidate table
- 5. Within 1 year:

- run gridder to produce resampled data cubes and ancillary files
- run extract2 for signal extraction from data cubes

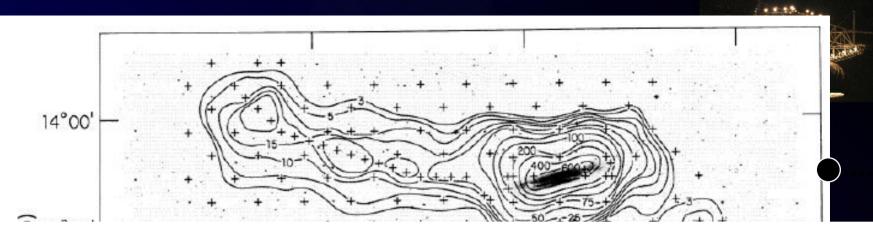




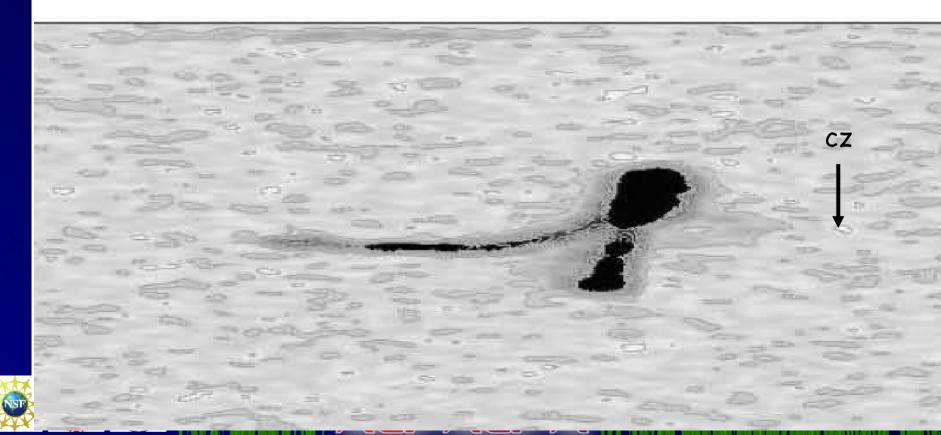


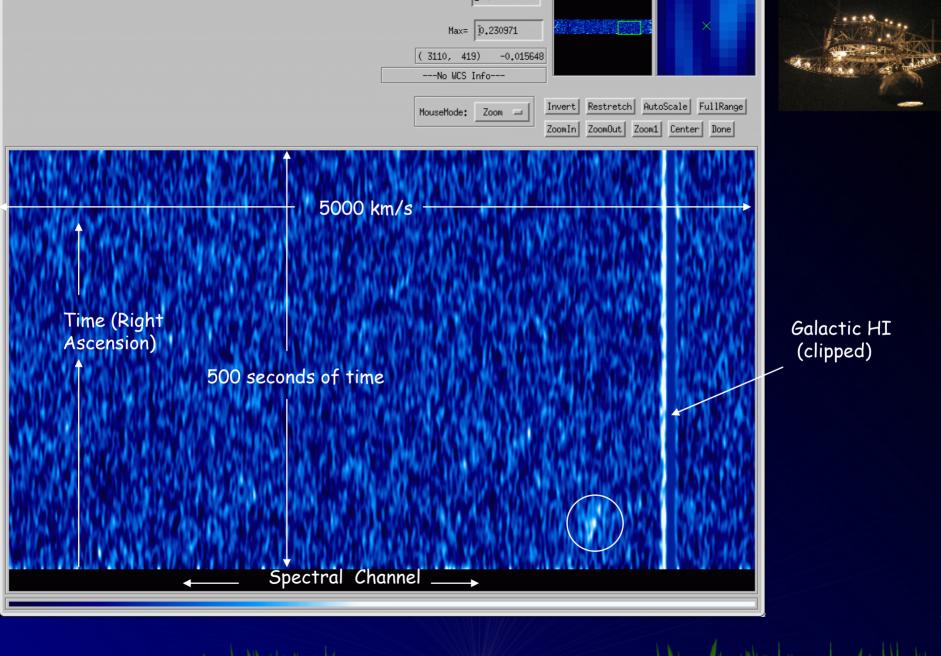


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## - Right Ascension

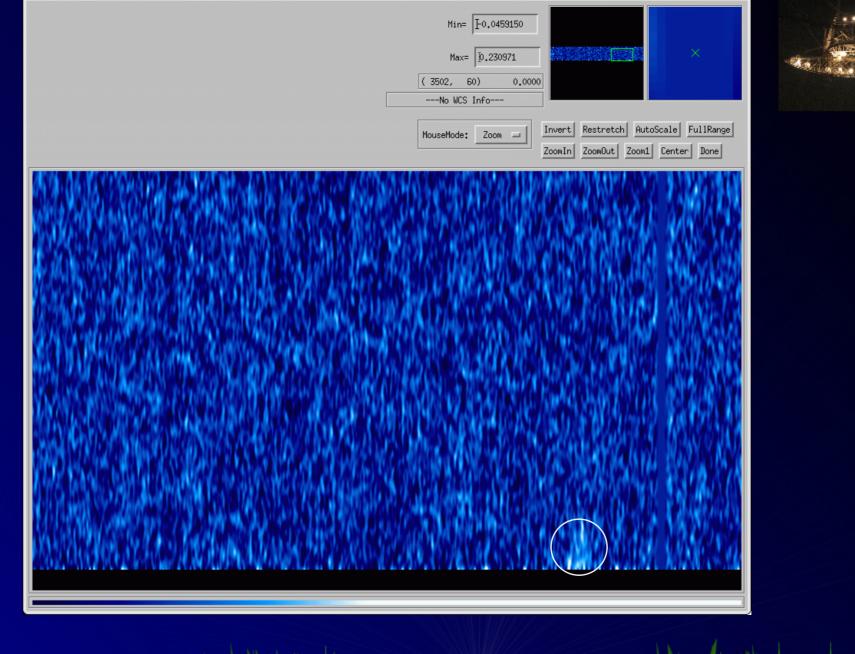




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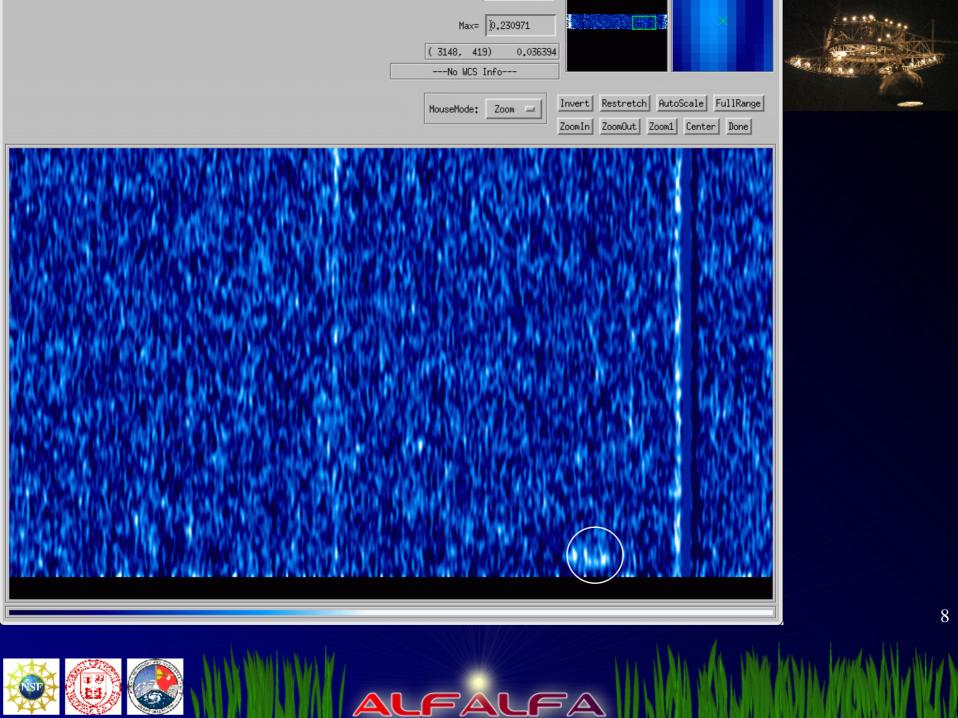
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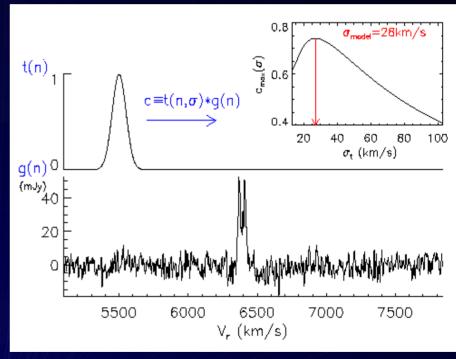






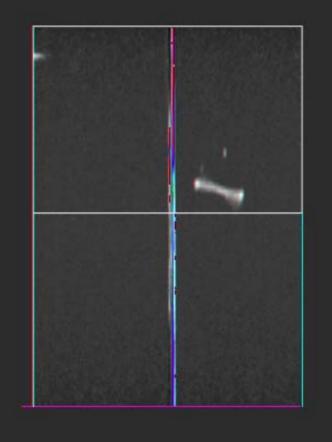
# Signal Extractor

- The signals are extracted by cross-correlations of a template with the spectra.
  - More sensitive than peakfinding algorithms.
    - sensitive to total flux, not just peak flux
    - Less vulnerable to baseline instabilities
    - especially important for low mass systems
  - Using FFT's, crosscorrelations are fast
  - It's a matched-filter algorithm



Slide: Amelie Saintonge

# NGC 2683 & co.



[Data cube visualization in KARMA by B. Kent]

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Things to do for ALFALFA - IDL:

- Procedure to process continuum sources in tiled region
- Signal-finding algorithm in 3d tile cubes: peak-finding, matched filter
- Signal-finding algorithm in 2d drift maps: peak-finding
- Map deconvolution of beam characteristics: "take the telescope out of the map"
- Matched-filter photometric/kinematic procedure
- Recovery of flux for large solid angle features, e.g. HVCs [Does anybody care about res=5 km/s Galactic HI?]
- Optimization of Destriping algorithms
- Procedures to overlay optical images on IDL/ATV HI maps, etc.
- Procedure to simultaneously fit all sources above given S/N in a tile cube
- Procedure to simultaneously fit all sources above given S/N in a drift map